

ECS455 Chapter 3

Call Blocking Probability

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Introduction

- The English dictionary word with the most consecutive vowels (six) is **EUOUAE**.
 - It is also the longest English word consisting only of vowels



- Imagine a word with **five** consecutive vowels.

Introduction

- Words with five consecutive vowels include **AIEEE**, **COOEEING**, **MIAOUED**, **ZAOUIA**, **JUSSIEUEAN**, **ZOOEAE**, **ZOAEAE**.



Introduction

- Words with five consecutive vowels include **AIEEE**, **COOEEING**, **MIAOUED**, **ZAOUIA**, **JUSSIEUEAN**, **ZOOEAE**, **ZOAEAE**.



- Our new topic: **QUEUEING** THEORY.
 - This is the only common word in the English language with five consecutive vowels.
- Note: The longest common word without any of the five vowels is RHYTHMS.
 - There are longer rare words: SYMPHYSY, NYMPHLY, GYPSYRY, GYPSYFY, and TWYNDYLLYNGS. WPPWRMWSTE and GLYCYRRHIZIN are long words with very few vowels.

That Second “e” ...

- You may recall the rule for changing a verb into its “–ing” form from your English class...
- If the verb ends in an “e” we remove the “e” and add “-ing”:
 - browsing, causing, changing, charging, choosing, giving, having, hiring

Queueing Theory

"queueing theory"

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Queueing theory

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viewpoints

Queueing theory is the mathematical stu



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Queuing Theory

Explore queuing theory for scheduling, resource allocation, and traffic flow applications

Queuing theory is the mathematical study of waiting lines or queues. This approach is applied to different types of problems, such as scheduling, resource allocation, and traffic flow. It is often applied in:

- Operations research
- Industrial engineering
- Network design
- Computer architecture

Limiting distribution

```
>> P = [2/5 3/5; 1/2 1/2]
```

```
P =
```

```
    0.4000    0.6000
    0.5000    0.5000
```

```
>> n1 = [0 1e5]
```

```
n1 =
```

```
    0    100000
```

```
>> n2 = n1*P
```

```
n2 =
```

```
    50000    50000
```

```
>> n3 = n2*P
```

```
n3 =
```

```
    45000    55000
```

```
>> n4 = n3*P
```

```
n4 =
```

```
    45500    54500
```

```
>> n5 = n4*P
```

```
n5 =
```

```
    45450    54550
```

```
>> n6 = n5*P
```

```
n6 =
```

```
    45455    54545
```

```
>> n1 = [1e4 9e4]
```

```
n1 =
```

```
    10000    90000
```

```
>> n2 = n1*P
```

```
n2 =
```

```
    49000    51000
```

```
>> n3 = n2*P
```

```
n3 =
```

```
    45100    54900
```

```
>> n4 = n3*P
```

```
n4 =
```

```
    45490    54510
```

```
>> n5 = n4*P
```

```
n5 =
```

```
    45451    54549
```

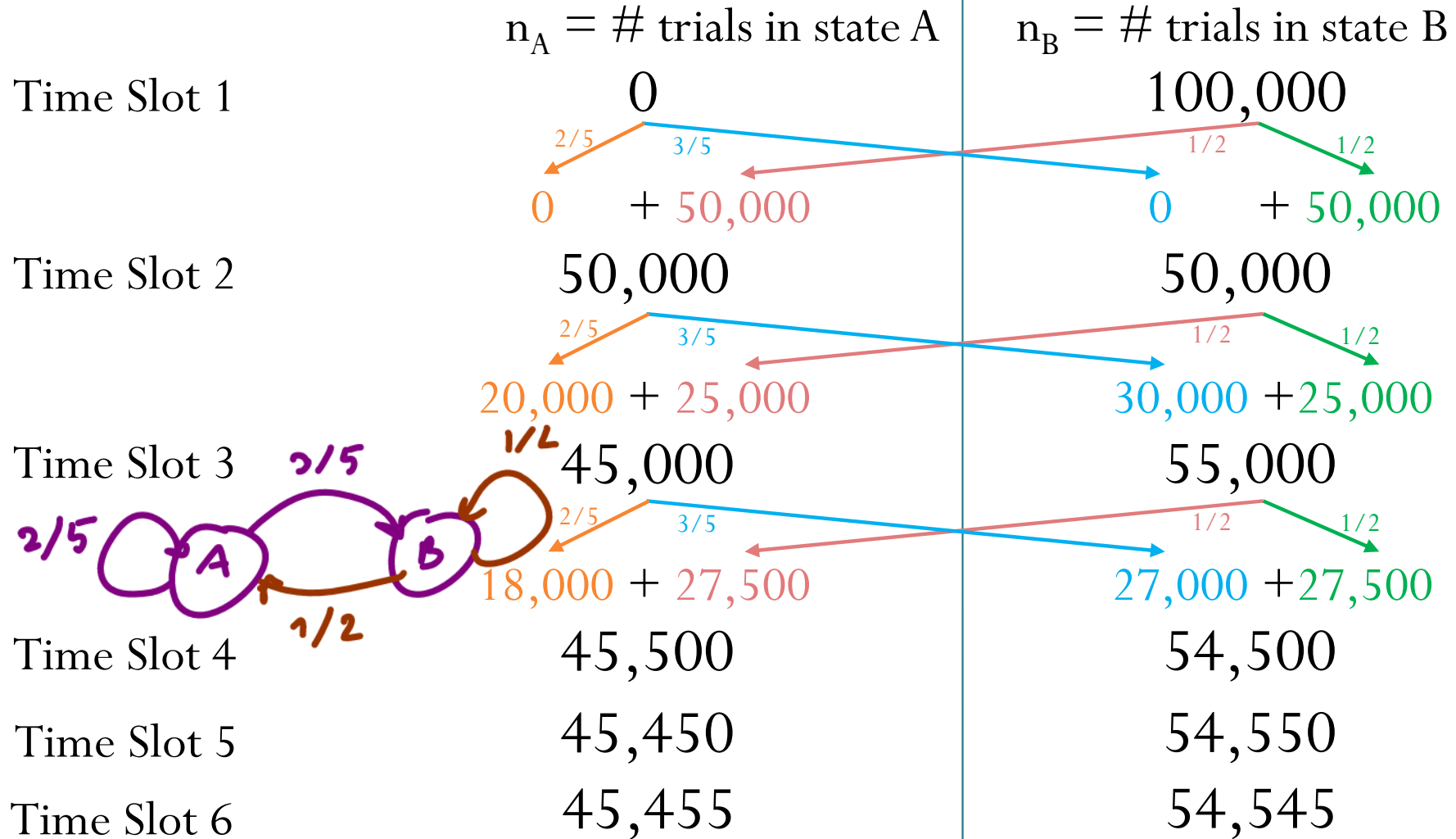
```
>> n6 = n5*P
```

```
n6 =
```

```
    1.0e+04 *
    4.5455    5.4545
```

$n^{(1)}$
 $n^{(2)} = n^{(1)} P$
 $n^{(3)} = n^{(2)} P = n^{(1)} P^2$
 $n^{(4)} = n^{(3)} P = n^{(1)} P^3$
 $n^{(5)} = n^{(4)} P^4$
 $n^{(6)} = n^{(5)} P^5$

Limiting distribution



time slot k
 $k+1$

$n_A^{(current)}$
 $\frac{2}{5}n_A + \frac{1}{2}n_B = n_A^{(new)}$

$n_B^{(current)}$
 $\frac{3}{5}n_A + \frac{1}{2}n_B = n_B^{(new)}$

$$\begin{bmatrix} n_A^{(new)} & n_B^{(new)} \end{bmatrix} = \begin{bmatrix} n_A^{(cur)} & n_B^{(cur)} \end{bmatrix} \begin{bmatrix} 2/5 & 3/5 \\ 1/2 & 1/2 \end{bmatrix}$$

Limiting distribution

```
>> P = [2/5 3/5; 1/2 1/2]
```

```
P =
```

```
    0.4000    0.6000
    0.5000    0.5000
```

```
>> n1 = [0 1e5]
```

```
n1 =
```

```
     0    100000
```

```
>> n2 = n1*P
```

```
n2 =
```

```
    50000    50000
```

```
>> n3 = n2*P
```

```
n3 =
```

```
    45000    55000
```

```
>> n4 = n3*P
```

```
n4 =
```

```
    45500    54500
```

```
>> n5 = n4*P
```

```
n5 =
```

```
    45450    54550
```

```
>> n6 = n5*P
```

```
n6 =
```

```
    45455    54545
```

```
>> P = [2/5 3/5; 1/2 1/2]
```

```
P =
```

```
    0.4000    0.6000
    0.5000    0.5000
```

```
>> P^2
```

```
ans =
```

```
    0.4600    0.5400
    0.4500    0.5500
```

```
>> P^3
```

```
ans =
```

```
    0.4540    0.5460
    0.4550    0.5450
```

```
>> P^4
```

```
ans =
```

```
    0.4546    0.5454
    0.4545    0.5455
```

```
>> P^5
```

```
ans =
```

```
    0.4545    0.5455
    0.4546    0.5455
```

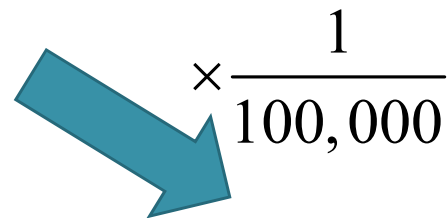
```
>> P^6
```

```
ans =
```

```
    0.4545    0.5455
    0.4545    0.5455
```

Limiting distribution

	$n_A = \#$ trials in state A	$n_B = \#$ trials in state B
Time Slot 1	0	100,000
Time Slot 2	50,000	50,000
Time Slot 3	45,000	55,000
Time Slot 4	45,500	54,500
Time Slot 5	45,450	54,550
Time Slot 6	45,455	54,545



$$\times \frac{1}{100,000}$$

	$p_A =$ proportion of trials in state A	$p_B =$ proportion of trials in state B
Time Slot 1	0	1
Time Slot 2	0.5	0.5
Time Slot 3	0.45000	0.55000
Time Slot 4	0.45500	0.54500
Time Slot 5	0.45450	0.54550
Time Slot 6	0.45455	0.54545

$$[v_A \ v_D] \begin{bmatrix} 5/11 & 6/11 \\ 5/11 & 6/11 \end{bmatrix} = \begin{bmatrix} 5/11 & 6/11 \\ 5/11 & 6/11 \end{bmatrix} P^2 = V D V^{-1} V D V^{-1} = V D^2 V^{-1}$$

Limiting distribution

$$P^3 = V D^3 V^{-1}$$

- Start with $P = \begin{bmatrix} 2/5 & 3/5 \\ 1/2 & 1/2 \end{bmatrix}$
- Want to find $\lim_{n \rightarrow \infty} P^n$.
- To do this, we first decompose P into $P = V D V^{-1}$.
 - In MATLAB, `[V,D] = eig(P)` produces a diagonal matrix D of eigenvalues and a matrix V whose columns are the corresponding eigenvectors.
- Finally,

```
>> P = sym([2/5 3/5; 1/2 1/2])
P =
[ 2/5, 3/5]
[ 1/2, 1/2]
P^n = V D^n V^-1

>> [V,D] = eig(P)
V =
[ -6/5, 1]
[ 1, 1]
D =
[ -1/10, 0]
[ 0, 1]
lim_{n to inf} D^n = [0 0; 0 1]

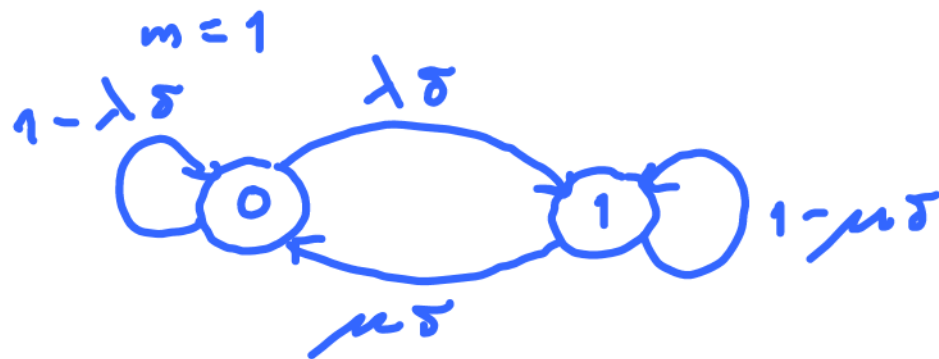
>> V*D*(V^(-1))
ans =
[ 2/5, 3/5]
[ 1/2, 1/2]
>> Dinf = sym([0,0;0,1])
Dinf =
[ 0, 0]
[ 0, 1]
>> V*Dinf*(V^(-1))
ans =
[ 5/11, 6/11]
[ 5/11, 6/11]
```

$$\lim_{n \rightarrow \infty} P^n = \lim_{n \rightarrow \infty} (V D V^{-1})^n = \lim_{n \rightarrow \infty} V D^n V^{-1} = V \left(\lim_{n \rightarrow \infty} D^n \right) V^{-1}$$

$$\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

Review: Discrete-Time Markov Chain

- We model the evolution in time of K by Markov chain.
 - $K(t) =$ the number of channels being occupied at time t
- Time is divided into small slots so that our analysis can be done in discrete time.
 - This only approximate the solution. However, the answers will be accurate in the limit that the slot size δ approaches 0.
- Discrete-time Markov chain can be specified via its **state transition diagram** or its **probability transition matrix P** .



$$P = \begin{bmatrix} 1 - \lambda\delta & \lambda\delta \\ \mu\delta & 1 - \mu\delta \end{bmatrix}$$

Simulating a Markov Chain in MATLAB

```
function X = MarkovChainGS(n,S,P,X1)
% n = the number of slots to be considered
% S = a row vector containing possible states (usually 1:N)
% P = transition probability matrix
% X1 = initial state for slot 1

N = length(S);           % Number of possible states
T = zeros(1,n);         % Preallocation
T(1) = find(S==X1);      % Express the states using indices from 1 to N
                        % instead of the provided support S
for k = 2:n
    T(k) = randsrc(1,1,[S;P(T(k-1),:)]);
end
X = S(T);               % Express the states using the provided support
end
```

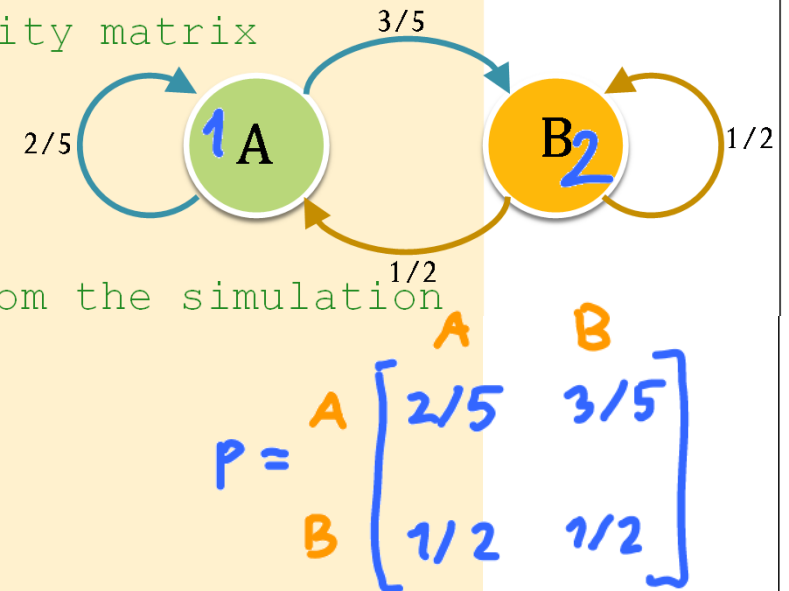
Simulating a Markov Chain in MATLAB

```
n = 1e1; % The number of slots to be considered
S = [1,2]; % Two possible states
P = [2/5 3/5; 1/2 1/2]; % Transition probability matrix
X1 = 2; % Initial state

X = MarkovChainGS(n,S,P,X1)

% Approximate the transition probabilities from the simulation
P_sim = []; x = X(1:(n-1)); y = X(2:n);
for k = 1:length(S)
    I = find(x==S(k)); LI = length(I);
    yc = y(I); cond_rel_freq = hist(yc,S)/LI;
    P_sim = [P_sim; cond_rel_freq];
end
P_sim

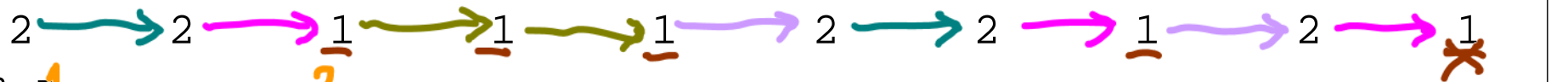
% Approximate the proportions of time that the states occur
p_sim = hist(X,S)./n
```



Simulating a Markov Chain in MATLAB

```
>> MarkovChain_Demo1
```

```
X = slot1 slot2 slot3
```



```
P_sim =
```

P_x

1	0.5000	0.5000
2	0.6000	0.4000

```
p_sim =
```

```
0.5000 0.5000
```

← The proportion of time that state 2 (B) occurs :

$$\frac{5}{10} = \frac{1}{2}$$

The proportion of time that state 1 (A) occurs :

$$\frac{5}{10} = \frac{1}{2}$$

Exercises

>> MarkovChain_Demo1

X =

2 1 2 1 2 1 2 1 1 1

P_sim =

	1	2
1	$\frac{2}{5} = 0.4$	0.6
2	1	0

There are 5 transitions from state 1

p_sim =

0.6	0.4
-----	-----

>> MarkovChain_Demo1

X =

2 2 2 2 1 2 2 2 1 1

P_sim =

0.5	0.5
$\frac{2}{7}$	$\frac{5}{7}$

p_sim =

0.3	0.7
-----	-----

Simulating a Markov Chain in MATLAB

```
n = 1e4; % The number of slots to be considered
S = [1,2]; % Two possible states
P = [2/5 3/5; 1/2 1/2]; % Transition probability matrix
X1 = 2; % Initial state
```

```
X = MarkovChainGS(n,S,P,X1);
```

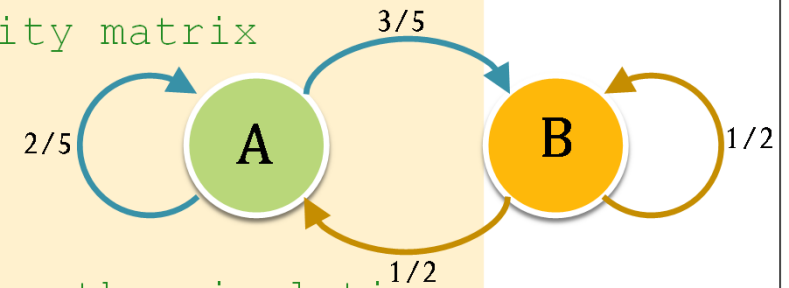
```
% Approximate the transition probabilities from the simulation
```

```
P_sim = []; x = X(1:(n-1)); y = X(2:n);
for k = 1:length(S)
    I = find(x==S(k)); LI = length(I);
    yc = y(I); cond_rel_freq = hist(yc,S)/LI;
    P_sim = [P_sim; cond_rel_freq];
end
```

```
end
P_sim
```

```
% Approximate the proportions of time that the states occur
```

```
p_sim = hist(X,S)./n
```



```
>> MarkovChain_Demo2
P_sim =
    0.4007    0.5993
    0.5055    0.4945
p_sim =
    0.4575    0.5425
```

≈ steady-state probabilities

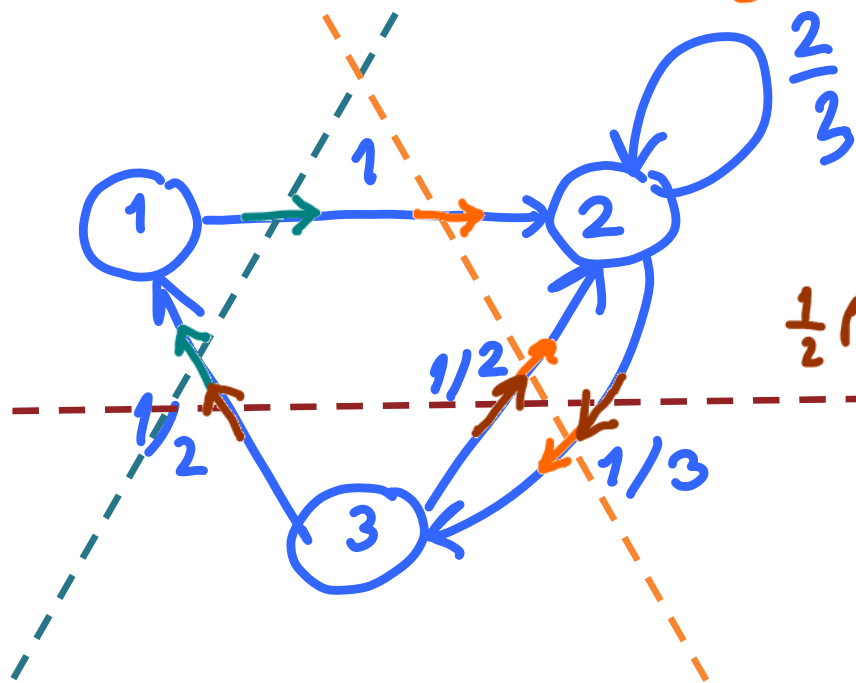
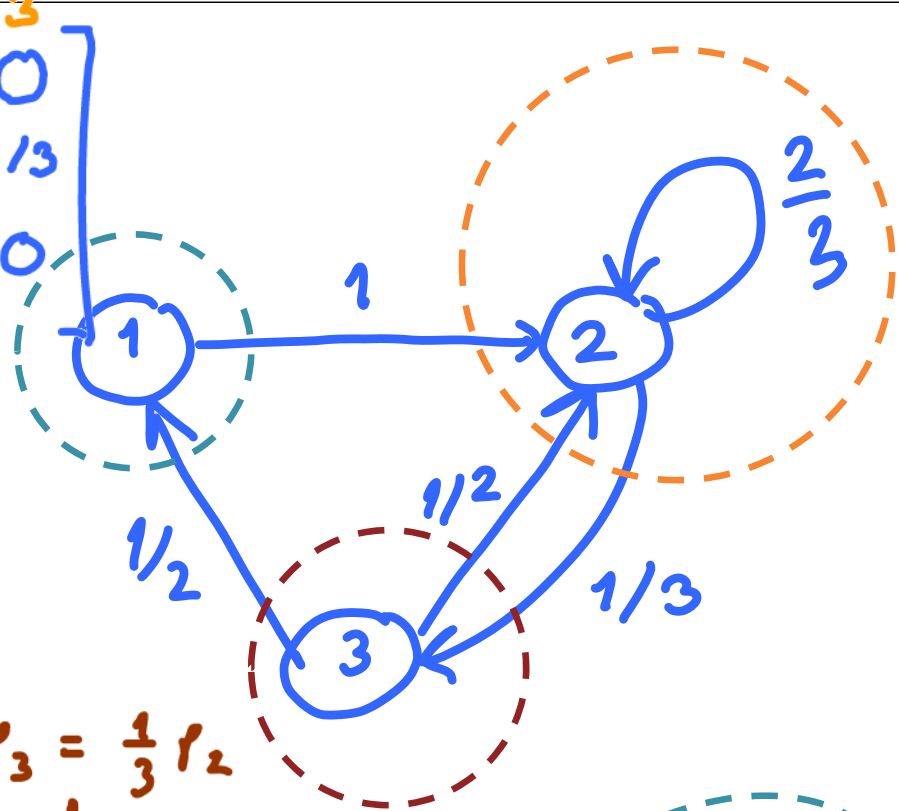
Review: Steady-State Probabilities

- Long-term behavior of a discrete-time Markov chain can be studied in terms of its **steady-state** (or limiting or equilibrium) probabilities.
 - To find these probabilities, we use balance equations together with the fact that
- To write down a **balance equation**,
 - first define a boundary,
 - then consider the transfer of probabilities “in” and “out” of the boundary.
 - To be at equilibrium, there should not be any net transfer.

Example

$$P = \begin{matrix} & \begin{matrix} 1 & 2 & 3 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \end{matrix} & \begin{bmatrix} 0 & 1 & 0 \\ 0 & 2/3 & 1/3 \\ 1/2 & 1/2 & 0 \end{bmatrix} \end{matrix}$$

$$p_1 \times 1 + p_3 \times \frac{1}{2} = p_2 \times \frac{1}{3}$$



$$\frac{1}{2} p_3 + \frac{1}{2} p_3 = \frac{1}{3} p_2$$

$$p_3 = \frac{1}{3} p_2$$

$$p_1 \times 1 = \frac{1}{2} p_3$$

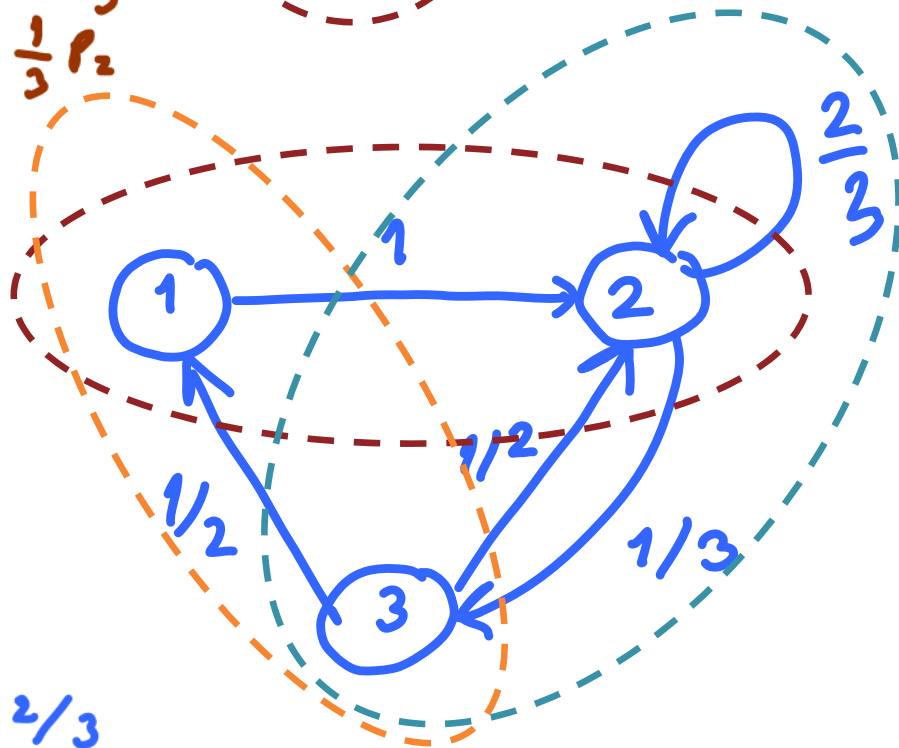
$$p_1 + p_2 + p_3 = 1$$

$$p_1 + 6p_1 + 2p_1 = 1$$

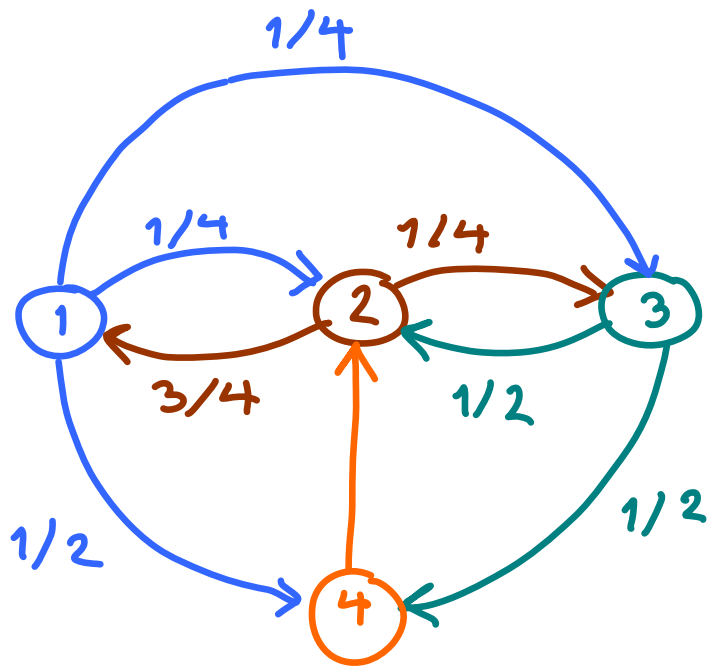
$$p_1 = 1/9$$

$$p_3 = 2p_1 = 2/9$$

$$p_2 = 6p_1 = 6/9 = 2/3$$



Exercise

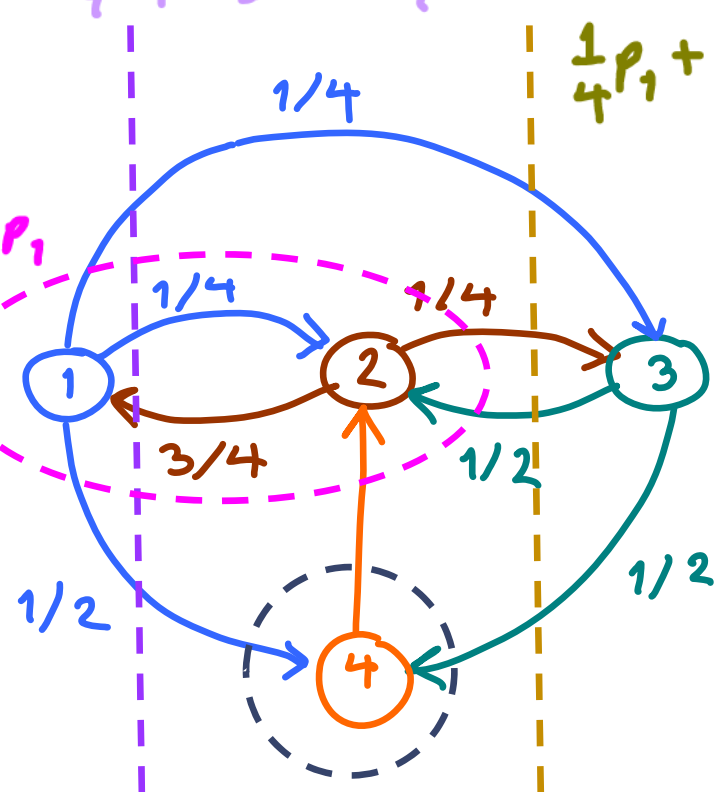


$$P_1 = \frac{3}{4} P_2$$

$$\frac{1}{4} P_1 + \frac{1}{4} P_1 + \frac{1}{2} P_1 = \frac{3}{4} P_2$$

$$\frac{1}{4} P_1 + \frac{1}{4} P_2 + \frac{1}{2} P_1$$

$$= \frac{1}{2} P_3 + P_4$$



$$\frac{1}{4} P_1 + \frac{1}{4} P_2$$

$$= \frac{1}{2} P_3 + \frac{1}{2} P_3$$

$$\frac{1}{2} P_3 + \frac{1}{2} P_1 = P_4$$

Review: Problem Solving

- For any question that requires you to get your answers (call blocking probability or steady-state probabilities) “from the Markov chain” or “via the Markov chain”, make sure that you
 - draw the Markov chain
 - set up the boundaries and write down the corresponding balance equations

Review: Two Interpretations

- Two Interpretations of **steady-state probabilities**:
When we let a system governed by a Markov chain evolve for a long time
 - at a particular slot, the probability that we will find the system in a particular state can be approximated by its corresponding steady-state probability,
 - considering the whole evolution up to a particular time, the **proportion of time that the system is in a particular state** can be approximated by its corresponding steady-state probability.

Example

```
n = 1e4; % The number of slots to be considered
S = [1,2,3]; % Three possible states
P = [0 1 0; 0 2/3 1/3; 1/2 1/2 0]; % Transition probability matrix
X1 = 2; % Initial state

X = MarkovChainGS(n,S,P,X1);

% Approximate the transition probabilities from the simulation
P_sim = []; x = X(1:(n-1)); y = X(2:n);
for k = 1:length(S)
    I = find(x==S(k)); LI = length(I);
    yc = y(I); cond_rel_freq = hist(yc,S)/LI;
    P_sim = [P_sim; cond_rel_freq];
end
P_sim

% Approximate the proportions of time that the states occur
p_sim = hist(X,S)./n
```

```
>> MarkovChain_Demo3
P_sim =
     0     1.0000     0
     0     0.6620     0.3380
    0.4858     0.5142     0
p_sim =
    0.1093     0.6657     0.2250
```

Review: Call-Blocking Probability

- **Call blocking probability P_b** is the (long-term) proportion of calls that get blocked by the system because all channels are occupied.
- For $M/M/m/m$ system, the (long-term) call blocking probability P_b is given by P_m
 - = the steady-state probability for state m
 - = the (long-term) proportion of time that the system will be in state m